



SCATS Priority Engine (SPE)

SCATS Priority Engine

SCATS Priority Engine (SPE) is a software application that enables the prioritisation of designated vehicles within SCATS controlled traffic networks.

SPE receives priority requests from external vehicle tracking systems and communicates these to the SCATS controller to ensure the enabled vehicle receives appropriate priority when moving through the road network.

SPE provides a unified signal priority function to vehicles including:

- Emergency vehicles
- Freight vehicles
- Mass public transport vehicles such as buses, trackless trams, and light rail
- VIP vehicles

SPE implements a set of rules that govern:

- Whether to accept or reject a given priority request
- How to combine priority requests for mutual benefit, where possible
- How to determine which vehicles have priority
- How to interact with SCATS to enact the priority request

Key features



Easy integration with SCATS core technology



Highly configurable options that can be tailored to the needs of individual cities



The ability to predefine which vehicles get priority when multiple requests are received



An interactive map and tables for real-time visibility of priority requests



Access to data for detailed analytics

How does SCATS Priority Engine work?

SCATS Priority Engine (SPE) is a highly configurable software that provides cities the ability to prioritise the movement of vehicles.

It provides a standardised interface to allow external vehicle tracking systems to issue requests on behalf of priority-designated vehicles. SPE receives the vehicles' estimated arrival time, entry lane, and departure lane, and then communicates with SCATS to ensure signals along the route remain green or change to green based on the estimated arrival time of the priority vehicle.

Should more than one vehicle request priority, SPE uses priority levels and scores to determine the order of priority and/or reject requests.



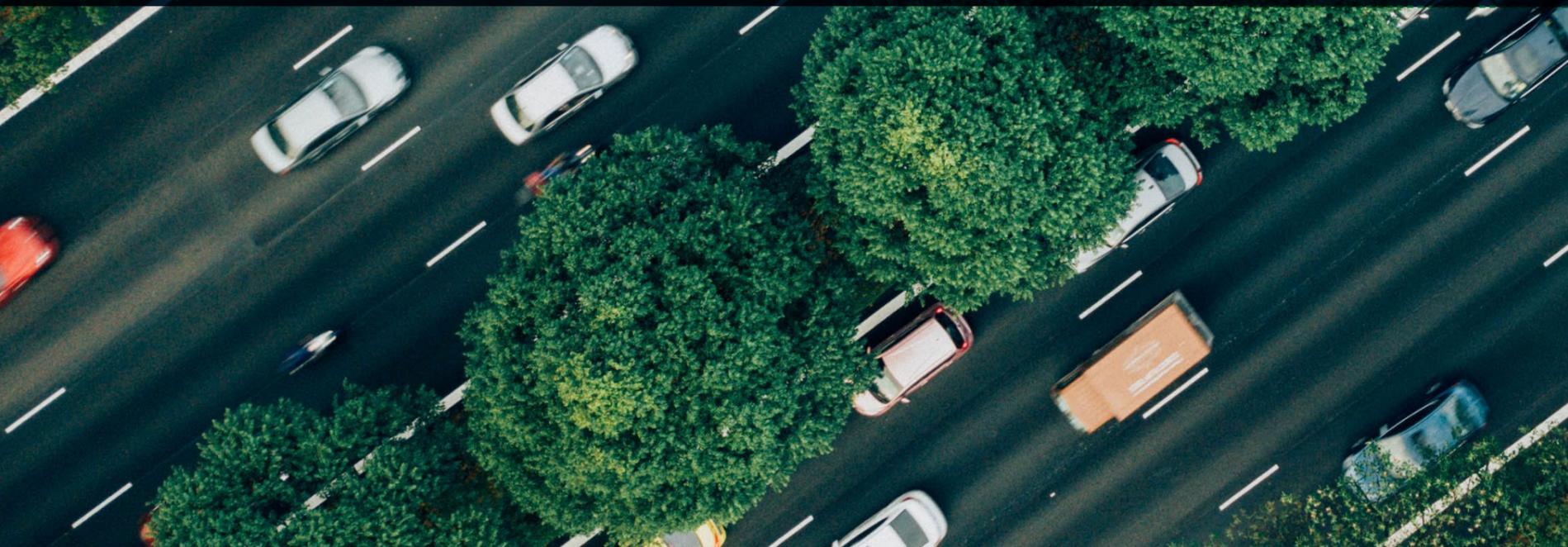
Network Priority Ecosystem



Modes of operation

SCATS Priority Engine (SPE) offers four modes of operation:

- 1. Dwell No Skip:** attempts to reach the requested phase quickly by running intermediate phases to a minimum.
- 2. Dwell Allow Skip:** attempts to reach the requested phase faster by skipping one or more of the intermediate phases, where possible.
- 3. Phase Insertion:** inserts the requested phase (that is not part of the cycle) immediately after the current phase.
- 4. Signal Group:** starts a specific signal group that is associated with one or more phases at a given site.



How can you use SCATS Priority Engine (SPE)?

- Priority can be applied to any intersection that is controlled by SCATS. This automatically creates a profile for priority features which defines constraints and/or privileges associated with vehicle types across different times of the day and different day types. Network operators can easily decommission (remove) or recommission priority managed intersections.
- Intersections can be configured by enabling priority, editing the profiles, or creating new profiles for the intersection.
- Vehicle types can be easily created and assigned a priority level.
- The progress of priority requests can be tracked using the map screen in SPE. The request status is displayed as coloured circles on the map.

Key

- Pending
- Awaiting movement, sent to SCATS waiting for green signal
- Request started
- Request ended and recovery period started

Priority statistics can be viewed for all successful (not rejected) requests for three time periods, displayed as 24 Hours, Today, and Last Hour. These statistics show the priority requests per intersection.

Other functions include:

- Adding new users, editing users, editing user passwords, and assigning profiles to users based on their authorisation to perform certain functions in SPE.
- Viewing active sessions to see which clients are active in the application.
- Creating a request explorer report which provides request information based on your designated filter criteria. This report can be exported as a CSV file.

- Viewing request information for a specific intersection. The Operations tab on the Intersection screen shows the last ten priority requests and continues to update as new requests are received. The intersection diagram will continually update according to the request Status for this intersection.
- Viewing the details of a specific priority request

Arrival time	Vehicle type	Movement(s)	Status	Details
Aug 18 08:52:18	HPR Bus	Ingress lane: 4, Egress lane: 7	OK	Details
Aug 18 08:49:12	HPR Bus	Ingress lane: 4, Egress lane: 7	Complete	Details
Aug 18 08:32:15	HPR Bus	Ingress lane: 1, Egress lane: 10	Complete	Details
Aug 18 08:31:22	HPR Bus	Ingress lane: 4, Egress lane: 7	Complete	Details

Timestamp	Type	Status	Info	Details
08:30:49	Priority request	-	-	Message
08:30:49	Priority acknowledgement	OK	Request OK	Message
08:30:49	Priority response	Pending	Request pending arbitration	Message
08:31:02	Update priority request	-	-	Message
08:31:02	Update priority response	OK	Request OK	Message
08:31:12	Priority response	In progress	Awaiting movement	Message
08:31:12	Update priority request	-	-	Message

Priority features

A priority feature is a privilege or a constraint that applies to different priority levels at different times of the day and different day types.

SCATS Priority Engine (SPE) has two types of priority features:

- **Privileges** apply to a given priority level and all levels **above** it.
- **Constraints** apply to a given priority level and all levels **below** it.

There are currently three identified priority features in SPE:

- **Priority Enabled** is a privilege that enables a priority at a site for a given (minimum) priority level and all priority levels above it.
- **Override Recovery** is a privilege that allows requests for vehicles with a priority level equal or larger than the minimum level to override the recovery interval. The recovery interval is the period at the end of a priority request at a site during which SPE will reject subsequent priority requests to allow the site to revert to normal operation.
- **Disabled Movements** is a constraint that disables priority on one or more movements at a site for vehicle types with priority levels at or below the maximum priority level. Priority will be enabled for that site for all other movements for the vehicle types configured for the first feature; Priority Enabled.

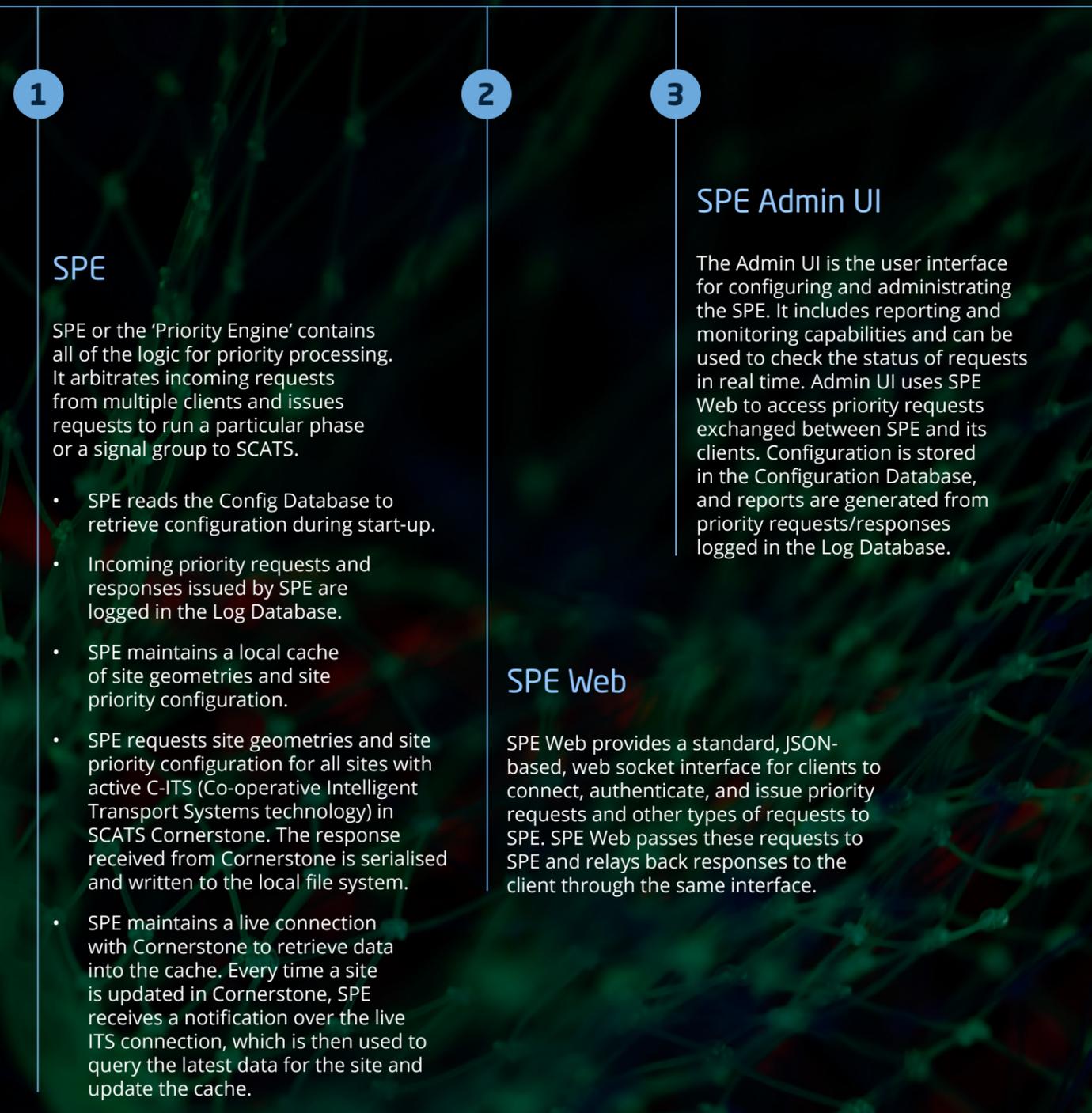
Priority scenarios

SCATS Priority Engine (SPE) handles four key scenarios:

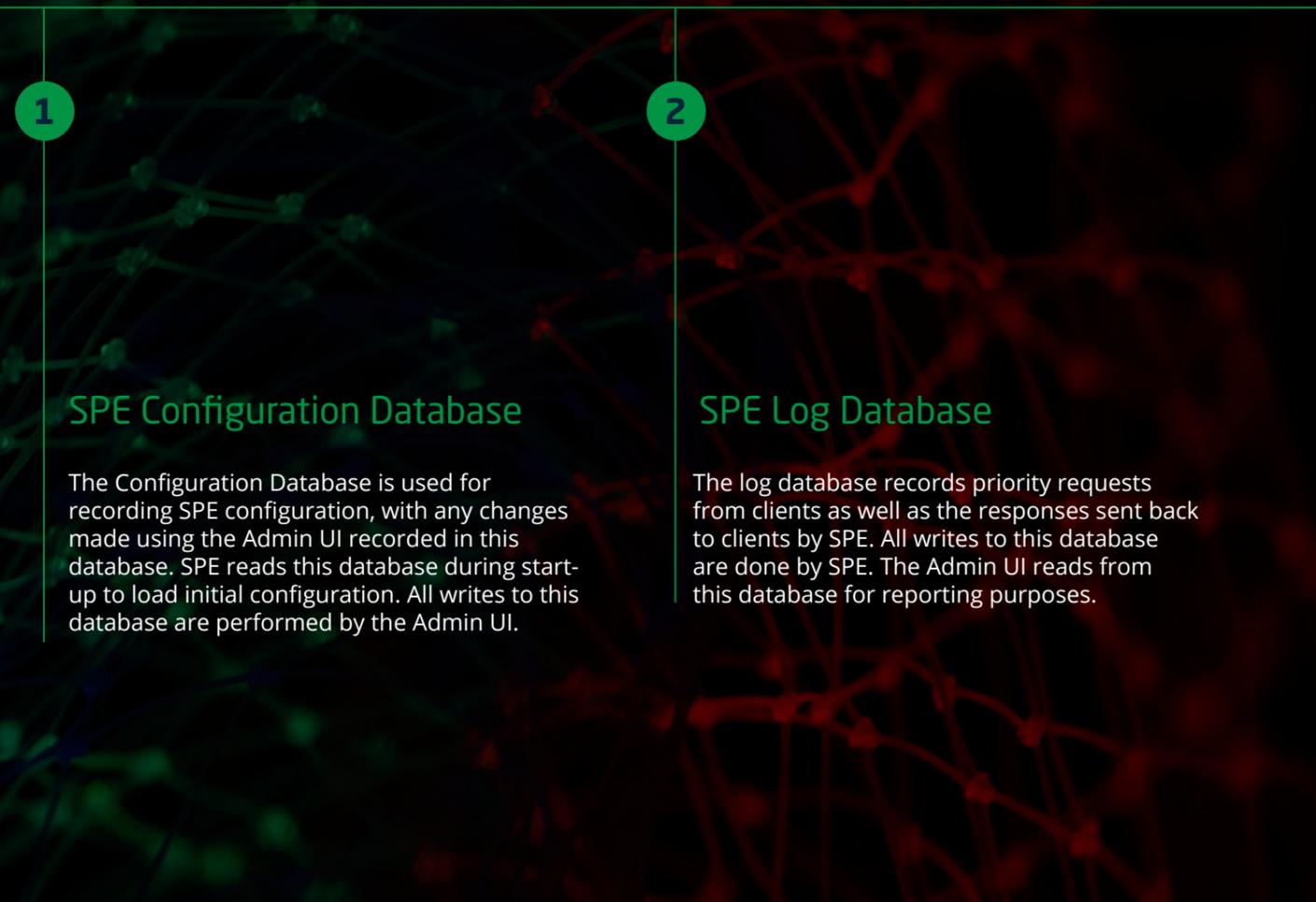
- **Basic:** SPE grants priority to a single request for a priority enabled vehicle.
- **Complementary:** SPE grants priority to two or more vehicles when there is at least one common phase that supports all required movements.
- **Conflicting:** SPE simultaneously receives requests from two or more vehicles at a given site along movements which do not share a common phase. SPE determines which vehicle to grant priority to, based on priority levels and scores.
- **Coupled:** a more sophisticated scenario where the vehicle tracking client can issue coupled requests at 2 or more subsequent intersections when the predictability of the travel time in the resulting path is high. This is usually the case when the path between the successive intersections is relatively short (150m or less) and there are no possible stoppages (e.g. bus stops) in between.

SCATS Priority Engine (SPE) Architecture

SPE is comprised of three components



SCATS Priority Engine also uses two separate Microsoft SQL databases



SCATS Priority Engine (SPE) can operate from the cache directly and does not need a live connection with Cornerstone to function. SPE can operate in offline mode provided there is data in the cache.



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